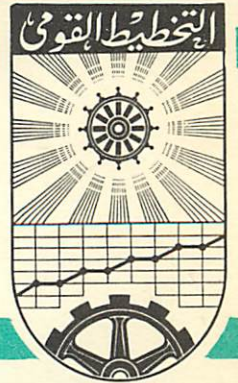


UNITED ARAB REPUBLIC

THE INSTITUTE OF NATIONAL PLANNING



Memo. No. 406
Notes on Interpolation
Formulae
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Part I.

The Lagrangian Interpolation Formula.

Section 1. Introduction:

Assume we are given $n+1$ values of a dependent variable "f" corresponding to $n+1$ values of independent variable "a". Denote these variables respectively

$$f(a_j), \quad a_j \quad \text{for } j=1,2,\dots,n+1. \quad \dots (1)$$

Then it is possible to construct a polynomial of degree n .

$$f(x) = A_0 + A_1 x + A_2 x^2 + \dots + A_n x^n. \quad \dots (2)$$

Such that:

$$f(x) = f(a_j) \quad \text{at } x = a_j. \quad \dots (3)$$

For numerical application, a more convenient form for the polynomial $f(x)$ is needed, which is derived in the following section.

Section 2. The Lagrangian Interpolation Formula:

From equations 2 & 3 we get the following $n+1$ equations

$$f(a_j) = A_0 + A_1 a_j + A_2 a_j^2 + \dots + A_n a_j^n. \\ j = 1, 2, \dots, n+1. \quad \dots (4)$$

The system of $n+2$ equations given by equation (2) & (4) are consistent if & only if

$$\begin{vmatrix} f(x) & 1 & x & x^2 & \dots & x^n \\ f(a_1) & 1 & a_1 & a_1^2 & \dots & a_1^n \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ f(a_j) & 1 & a_j & a_j^2 & \dots & a_j^n \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ f(a_{n+1}) & 1 & a_{n+1} & a_{n+1}^2 & \dots & a_{n+1}^n \end{vmatrix} = 0. \quad \dots(5)$$

Expanding the above determinant columnwise we have

$$f(x) \cdot \Delta_0 = \sum_{j=1}^{n+1} f(a_j) \cdot \Delta_j^{\wedge}(x) \cdot (-1)^{j+1}. \quad \dots(6)$$

Where

$$\Delta_0 = \begin{vmatrix} 1 & a_1 & a_1^2 & \dots & a_1^n \\ 1 & a_2 & a_2^2 & \dots & a_2^n \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_j & a_j^2 & \dots & a_j^n \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{n+1} & a_{n+1}^2 & \dots & a_{n+1}^n \end{vmatrix} \quad \dots(7)$$

and $\Delta_j(x)$ is the determinant given in the right-hand side of equation 6.

For example:

$$\Delta_3 = \begin{vmatrix} 1 & x & x^2 & \dots & x^n \\ 1 & a_1 & a_1^2 & \dots & a_1^n \\ 1 & a_2 & a_2^2 & \dots & a_2^n \\ 1 & a_4 & a_4^2 & \dots & a_4^n \\ 1 & a_5 & a_5^2 & \dots & a_5^n \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{n+1} & a_{n+1}^2 & \dots & a_{n+1}^n \end{vmatrix} \dots (8)$$

Notice that $\Delta_j(x)$ is a polynomial of degree n , and hence can in general be expressed in the form

$$\Delta_j(x) = C_j(x - c_1)(x - c_2) \dots (x - c_n). \dots (9)$$

From the determinantal definition of $\Delta_j(x)$, it is seen that

$$\Delta_j(x) = 0 \dots (10)$$

at the n values of x given by

$$x = a_i \quad i \neq j \dots (11)$$

From (9), (10) & (11) we can put

$$\begin{aligned} c_i &= a_i & i < j \\ c_i &= a_{i+1} & i \geq j \end{aligned} \dots (12)$$

Or in other words

$$\Delta_j(x) = \frac{C_j}{(x-a_j)} \cdot \prod_{j=1}^{n+1} (x - a_j) \quad \dots (13)$$

$$= \frac{C_j}{(x-a_j)} \cdot P_n(x) \quad \dots (14)$$

where

$$P_n(x) = \prod_{j=1}^{n+1} (x - a_j) \quad \dots (15)$$

Consider the determinant Δ_0 . By analogy it can be expanded in a similar way as $\Delta_j(x)$ and this can take the following form:

$$\Delta_0 = C_j \prod_{i=1)j(n+1)} (a_j - a_i) \quad \dots (16)$$

where $i = 1) j (n+1$ stands for $i = 1, 2, \dots, j-1, j+1, \dots, n+1$.

From the above definition of $p_n(x)$ it can be seen that

$$\Delta_0 = C_j \left[\frac{d P_n(x)}{dx} \right]_{x=a_j} = C_j P'_n(a_j) \quad \dots (17)$$

From (14) & (17) we can put

$$L_j(x) = \frac{\Delta_j(x)}{\Delta_0} = \frac{1}{(x-a_j)} \cdot \frac{P_n(x)}{P'_n(a_j)} \quad \dots (18)$$

Substituting the above equation in equation (6) defining the function $f(x)$, we obtain the following convenient expression for the function $f(x)$.

$$f(x) = \sum_{j=1}^{n+1} L_j(x) f(a_j) \quad \dots (19)$$

This formula is the wellknown "Lagrangian Interpolation Formula".⁽¹⁾

Section 3 : Computation procedure:

The above Lagrangian interpolation formula had been programmed on the I.B.M. 1620 using Fortran Language.

Section 3.1 gives the symbols used in the Fortran program and the way the data must be prepared.

Section 3.2 gives the block diagram.

Section 3.3 gives the program itself in the Fortran Language.

Section 3.4 gives a numerical example.

The program available can handle interpolation by Lagrangian formula provided the number of points at which the function is given is less or equal to 100. If we have more points, equal in value to the integer J1, then we must change the first dimension statment in the source program to the following statment

```
DIMENSION A(J1), F(J1)
```

and of course we have to compile the program again to get the object program.

1) See Kopal, Zdenek
Numerical analysis, 2nd. ed. N.Y., Wiley, 1961.

Section 3.1 : Symbols used in the program and the preparation of data.

The formula is

$$f(x) = \sum_{j=1}^{n+1} L_j(x) f(a_j)$$

where

$$L_j(x) = \frac{(x-a_1)(x-a_2)\dots(x-a_{j-1})(x-a_{j+1})\dots(x-a_{n+1})}{(a_j-a_1)(a_j-a_2)\dots(a_j-a_{j-1})(a_j-a_{j+1})\dots(a_j-a_{n+1})}$$

Symbols in Theory	Corresponding Symbols in Fortran
n+1	N1
j	J
a _j	A(J)
f(a _j)	F(J)
x	X
f(x)	FX

The preparation of data:

The first card must contain the number N1 of values at which the function is given and the code of the process as following:

N1 : Column 1 → 3 xxx integer form.
 Code : Column 4 → 10 xx.xxxx floating form.

After the first card we have N1 cards each corresponding to one given value of the function.

The data in these N1 cards are as following:

J	:	column	1 → 3	xxx	integer form
A(J)	:	column	4 → 17	<u>+</u> x.xxxxxxxE <u>+</u> xx	E form
F(J)	:	column	18 → 31	<u>+</u> x.xxxxxxxE <u>+</u> xx	E form

After the N1 cards, we have cards, each corresponding to the value of the argument X at which we want to determine our function.

The data in these cards are as following:

X	:	column	1 → 14	<u>+</u> x.xxxxxxxE <u>+</u> xx	E form
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So if our problem is to interpolation for M1 values, given N1 values of the function, then our data cards will be

$$1 + N1 + M1 .$$

Section 3.2

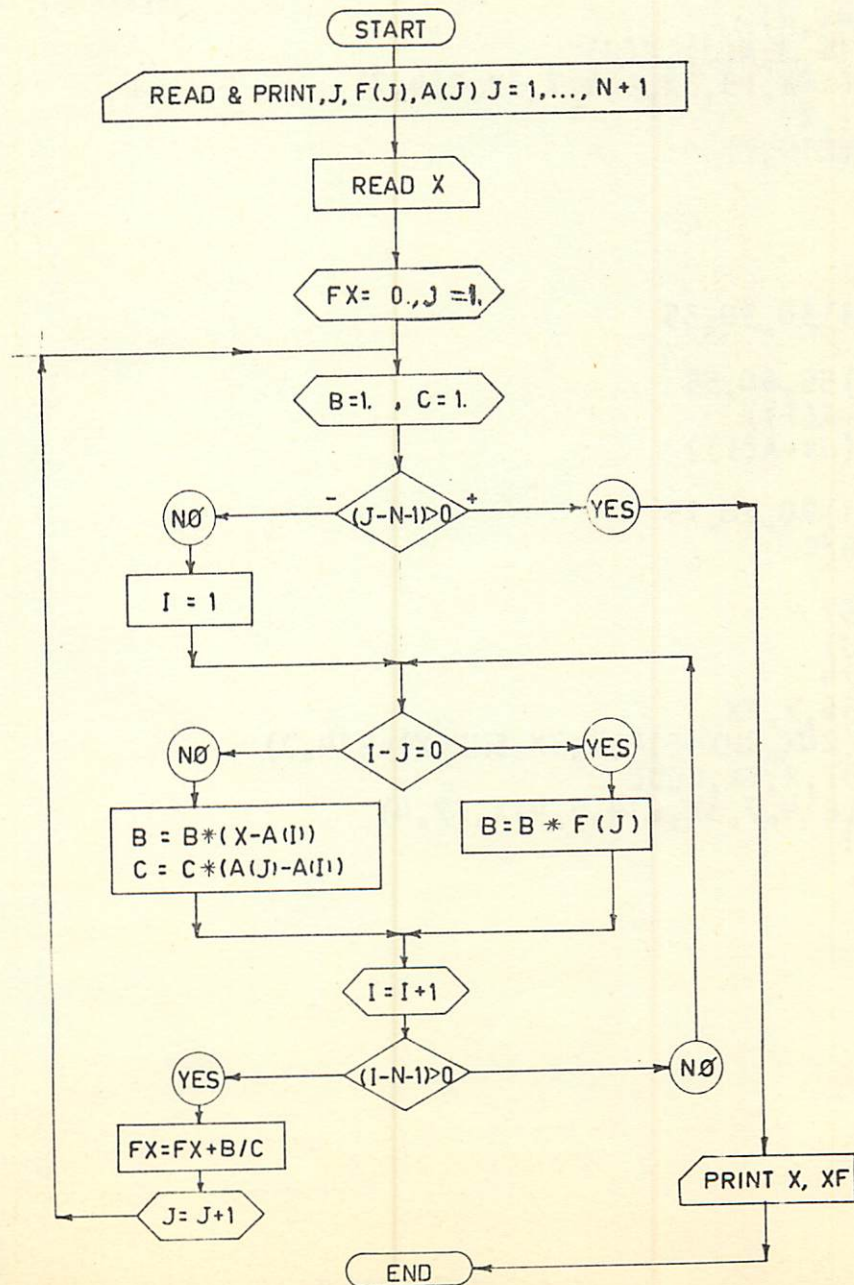
Block diagram of Lagrangian.

THE FLOW CHART FOR INTERPOLATION BY LAGRANGIAN FORMULA

GIVEN THE VALUES $f(a_j)$ OF A FUNCTION $f(x)$ AT GIVEN
POINTS a_j FOR $j=1, \dots, N+1$, TO DETERMINE

$$f(x) = \sum_j \frac{(x-a_1) \dots (x-a_{j-1})(x-a_{j+1}) \dots (x-a_{n+1})}{(a_j-a_1) \dots (a_j-a_{j-1})(a_j-a_{j+1}) \dots (a_j-a_{n+1})} f(a_j) \text{ FOR GIVEN } x$$

PUT $f(a_j) = F(J)$, $a_j = A(J)$ AND $F(X) = FX$, $X = X$



C THE FOLLOWING IS A FORTRAN PROGRAM TO INTERPOLATE BY LAGRANGIAN FORMUL
 C THE NUMBER OF POINTS USED IN INTERPOLATION IS LESS THAN 100

```

    DIMENSION A(100),F(100)
    READ 10,N1,CODE
10  FORMAT(13,F7.4)
    DO 11J=1,N1
11  READ 12,J,A(J),F(J)
12  FORMAT(13,2E14.7)
    PRINT 13
13  FORMAT(59H
    XATA)
    PRINT 14
14  FORMAT(52H
    DO 15J=1,N1
15  PRINT 16,J,A(J),F(J)
16  FORMAT(20X,13,3X,E14.7,3X,E14.7)
1  READ 17,X
17  FORMAT(E14.7)
    FX=0.
    J=1
57  B=1.
    C=1.
    IF(J-N1)30,30,35
30  I=1
70  IF(I-J)55,60,55
55  B=B*(X-A(I))
    C=C*(A(J)-A(I))
74  I=I+1
    IF(I-N1)70,70,75
75  FX=FX+B/C
    J=J+1
    GO TO 57
60  B=B*F(J)
    GO TO 74
35  PRINT 36,X,FX
36  FORMAT(20X,2HX=E14.7,3X,5HF(X)=E14.7)
    PUNCH 37,X,FX,CODE
37  FORMAT(E14.7,3X,E14.7,41X,F7.4)
    GO TO 1
  END
  
```

THE FOLLOWING ARE THE D

J	A(J)	F(J))
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THE FOLLOWING ARE THE DATA

J	A(J)	F(J)
1	1.0000000E+00	0.0000000E-99
2	9.0380000E-01	2.2030000E-01
3	8.0920000E-01	4.2130000E-01
4	7.2870000E-01	5.7930000E-01
5	6.6790000E-01	6.7560000E-01
6	5.8470000E-01	7.6730000E-01
7	4.8290000E-01	8.5650000E-01
8	3.7100000E-01	9.2660000E-01
9	2.4800000E-01	9.7180000E-01
10	7.6500000E-02	9.9450000E-01

X= 5.0000000E-01 F(X)= 8.4171143E-01

Part II.

Aitken's Interpolation Formula.

Section 1. Introduction:

Aitken's Algorithm for the Lagrangian Interpolation Formula:

There is an algorithm, due to Aitken, for computing Lagrangian interpolation formula, which is suitable for digital computers & even desk calculators. Given the function $f(a_j)$ at the $n+1$ points a_j ($j=1,2,\dots,n+1$), Aitken's algorithm for computing the lagrangian interpolation formula $f(x)$ whose numerical values at that is satisfied at the point $x=a_j$ ($j=1,\dots,n+1$) coincides with the values $f(a_j)$, proceeds as following:

The Lagrangian interpolation formula of degree r :

$$f(x | a_1, a_2, \dots, a_r, a_t) \quad n+1 \geq t \geq r+1 \quad \dots (1)$$

which numerically is equal to the function $f(x)$ at the points:

$$x=a_1, a_2, \dots, a_r, a_t. \quad \dots (2)$$

can be obtained from the two Lagrangian interpolation formulae of degree $r-1$:

$$f(x | a_1, a_2, \dots, a_{r-1}, a_r) \quad \dots (3)$$

$$\& \quad f(x | a_1, a_2, \dots, a_{r-1}, a_t) \quad \dots (4)$$

that passes respectively through the two following sets of points:

$$a_1, a_2, \dots, a_{r-1}, a_r. \quad \dots (5)$$

$$\& \quad a_1, a_2, \dots, a_{r-1}, a_t. \quad \dots (6)$$